

## Implementing Expert Systems for Process Control

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### Introduction

Expert Systems can be used in process control for advisory analysis, and control functions. Specific examples include advanced control strategies, alarm management and interpretation, operator procedure advisors, process diagnostics and generation of alarms when the process is approaching the boundary of the normal operating environment.

An expert system encapsulates the problem solving power of a human who has the specific knowledge to solve problems of a specific domain. This could be the medical diagnostic knowledge of a physician. It could be the knowledge of a structural engineer who designs offshore oil platforms.

More to the point of this paper, an expert system could use the plant engineer's knowledge of how a plant is supposed to work to solve operating problems. The expert system can also use the senior plant operator's pragmatic knowledge of how the plant actually works and what operating procedures emanate from the most pressing problems.

The plant gains several advantages by using an expert system rather than relying on direct human problem solving.

**Experts are rare.** The senior operators are not always on shift when the problem occurs. The control

engineer may not work at the plant where the problem happens. The solution may require the combined knowledge of two or more experts.

**People's focuses of attention are variable.** The plant operator may not be paying close attention at the time the problem develops or may focus too long on the wrong hypothesis.

**People's scopes of attention are variable.** A problem which an experienced operator can solve quickly may be too complex for another operator.

**Human response time is limited.** If humans can not readily respond quickly enough to certain problems, the question becomes whether an expert system would be faster.

**Human decision making is variable.** Sometimes there may be more than one adequate solution to a problem. When an expert picks one correct solution one time and a different one at other times, the solution approach can remain a mystery to someone who watches and tries to learn from the expert. The very act of building an expert system, however, is the act of formalizing the knowledge. This formal representation of the problem solution approach can be a vehicle for studying how to improve the approach.

## Expert System Versus Other Software

The foregoing reasons for using expert systems apply to other forms of process control software such as functional block systems and procedural languages

*Functional block systems are designed specifically to solve control problems. These systems have been refined so that they handle very complex control problems. They also allow the controller to interact with the process in a manner similar to that of a human operator. The more common procedure to be solved, the easier it is to solve with functional blocks. But, when an unusual problem is to be solved, the use of the functional blocks can be very limiting.*

Procedural programming languages (e.g. BASIC, FORTRAN, C) provide great flexibility. But, unlike functional blocks, they are not the language of the controller. Writing the code can take a long time. Writing these programs takes a somewhat different talent from controller engineering. Procedural languages force the developer to think in terms of procedures

even though the control problems probably not inherent y procedural

The EXPERT 90 process control expert system development package described in this paper provides flexibility in certain areas not provided by functional block systems. It allows complex logic to be more easily and understandably implemented with the provision of more efficient processing of the logic. It provides operator manipulations when the input data is fuzzy or transient.

The expert system editor provides a language which is closer to the task of making control decisions than are procedural languages. It allows the application developer to directly describe the solution to the problem and eliminates the job of programming the problem so it can be translated into a procedural language. This results in dramatic productivity improvements in implementing control strategies.

## Special Requirements of Process Control Expert Systems

Expert systems which handle process control problems must meet a specific set of requirements

- Process input and output
- Time real time
- Manage uncertainty data
- Response time
- Operator interface
- Knowledge engineering interface

The expert system must access the process information. This access must be online and real time so that the expert system can provide users with more answers than questions. It must be efficient so that it remains within the capacity of the communication system.

Data must be represented in relation to time. Operations must take the age of the various data items into account. The expert system may need to recognize patterns in the time trend of data.

Real time systems are normally described in concrete terms even when the actual data is not that certain. For example, the statement "tank level is high when level exceeds 20 feet" implies that a tank level of 19.90

feet is not high. Yet a process controller might consider a level of 19.90 feet rather high. A process control expert system must be able to deal with such uncertainties.

The expert system must respond in real time to control actions and its operator advice must be given before the problem grows and while its output is available.

The operator interface must be straightforward. The expert system must not impose a new set of displays on the operator which are different from the displays used for the rest of the control system.

The knowledge engineering tools must be straightforward. The knowledge to be embodied in the expert system is held by the plant engineer and the experienced plant operator. These people must build the expert system naturally and maintain it. They must be able to use the knowledge engineering tools themselves. If a knowledge engineering specialist were required, the natural implementation would become more expensive and maintenance would become impossible.

## Real Time Challenges

As mentioned before, an expert system which solves problems of a process in real time has a more stringent response time requirement. The specific response time requirements depend upon the application. An expert system for interpreting alarms must handle many inputs during an upset and produce results in less than one second. By contrast, diagnosis between many kinds of equipment wear takes a smaller set of inputs and only needs to be done every few hours.

An inference engine has a different efficiency problem than does function block systems. Function block systems typically iterate through sections of function blocks which the application designer has defined. The iteration is routine and the real time challenges are answered by having the individual function block handlers be efficient. But the inference engine does not routinely iterate through sections of knowledge. Instead, it compares the conditions of the rules with patterns of existing data so that can dynamically pick a sequence of execution of the rules in the process. It allocates memory very dynamically in tiny pieces but uses most of those pieces very briefly. The inference engine has a non-trivial pro-

blem in recognizing which pieces of memory are available for use.

Inference engines typically solve the memory organization problem by stopping the processing of the application from time to time to reorganize. They typically do this reorganization when the problem is solving its most intense because that is when memory is being allocated the most dynamically. This approach is not acceptable for a process control application that would often begin the analysis of a process upset only to pause for some time to reorganize memory.

The situation in which a process expert system's evaluation may still be developing as conclusions are being drawn in a process upset many process points change rapidly. They may continue to change long after a diagnosis is required of the expert system. Yet some of the changing data continues to be relevant. The expert system must present preliminary conclusions within seconds. But then it must modify its conclusions as the data continues to change. It must modify its conclusions in a logical and not haphazard way. It must deal with changing data without recomputing everything from the start.

## The Inference Engine Integrated into the DCS

To meet these requirements, the expert system must be online for a person's required to enter the process data into the expert system as in Fig 1a then none of the runtime advantages of expert systems is met. At best, the system is useful for abstracting the concept of a prototype knowledge base.

The popular technique for putting an expert system online is to run the expert system on a host computer and interface the host computer to a gateway of the control system as in Fig 1b. Now the data stream and benefits can be realized from the automatic nature of the system. Unfortunately, this is at the expense of the host computer and providing interface hardware and software increases the communication load on the system and suffering the delays in data transmission imposed by the communication system. The system can be designed so that the operator can use the standard control console to access the results of the expert system. However, the expert system shells are normally offered with a great emphasis on the presentational availability through the rowndisplay terminal. As such, the operator may have to monitor a terminal of the expert system which uses a very different set of conventions from the standard control console.

The EXPERT 90 inference engine described in this paper, Fig 1c, runs in standard distributed control system hardware. Its rules share the same memory as the function blocks that are processed by the same processor chip. The expert system runs as a block in the module's configuration as shown in Fig 2.

Embedding the inference engine eliminates a lot of the data interface problems. The data is ready in the same hardware module. There is no additional hardware, software, or transmission delay.

The operator's access to the expert system is through standard graphical displays of the control system console. To the operator, the expert system is a homogeneous part of the control system.

Embedding the expert system also has side benefits. It minimizes the types of hardware which the plant personnel need to maintain, eases the expansion of the expert system, and minimizes the incremental cost. Finally, redundant expert systems become low cost practical options by using the redundancy features of the distributed control system.

## Knowledge Representation

Application on knowledge the knowledge about how to solve a specific problem is represented as a set of rules in an expert system the application developer does not need to specify a sequence of execution for the rules. Rather each rule expresses a relationship among information. This freedom to add additional rules at any place is a major factor in the productivity gains afforded by expert system programming over procedural language programming.

Fig 3 shows a sampling of rules. Rules can express logic with expressions which use AND OR and NOT. The operators SET and CLEAR are used when the value of the variable in the conclusion is to be remembered even after the condition is no longer true. The use of English like variable names allows both plant engineers and plant operators to understand the resulting knowledge base.

Temporal relationships are expressed both in the conditions and the conclusions. FOR n SECONDS is a condition that makes sure a condition is sustained before taking action. JUST NOW is used when only the transition from false to true is important. AFTER n SECONDS causes an action before the conclusion is satisfied. FOR n SECONDS in the conclusion sustains the conclusion.

So let us data is not certain. Fig 4 shows examples which deal with this. The expert may say that rpm is unusual if it is above 250. This does not mean that 249 is not unusual. Perhaps 230 is definitely not unusual. But between 230 and 250 is an uncertain area. The knowledge representation language allows this to be expressed and then allows straightforward logic rules to deal with the part a certainty.

## The Engineering Workstation

The plant engineer and the senior plant operator can develop the expert system directly. They are the experts and are also the people who maintain the expert system. Since they are the ones who use and/or benefit from the expert system they personally know the aspects of the expert system that need to be upgraded. The knowledge representation language should be kept close to English to avoid making the application developer learn an arcane language.

The application developer constructs the knowledge base at a workstation which is separate from the module which will execute the knowledge base. This is the same workstation which the engineer uses to develop traditional control function block configurations on a BM PC AT or compatible with 640K memory. The workstation needs to be connected to the control system only when the knowledge base is

being transferred. The workstation sends the knowledge base to the selected standard control module in the distributed control system. When the module executes the knowledge base the services of the workstation are no longer required.

The EXPERT 90 knowledge base editor guides the application developer through the language. As statements are entered the developer is presented with menus of the specific items which can be edited to the statement at the current point of editing. The editor keeps track of variable names as the developer uses them. The editor recognizes the type of variables from the usage of the variable rather than demanding that the developer define variables before using them. The editor finds errors as they are typed rather than presenting the developer with a summary of errors at the end of editing.

## Conclusion

Expert systems can be used to solve control problems. The real-time nature of these applications imposes a specific set of requirements on the expert system. The expert system must access the process information in a timely manner and must be represented in real-time. Conclusions must be drawn quickly.

An expert system development tool has been developed to answer these concerns. The inference engine of EXPERT 90 runs in the same distributed

control system module as the conventional control. This eliminates communications problems and gives the plant operator a single window to the process. The knowledge in an expert system is represented as rules which may involve time relationships. The rules may also involve uncertain data. Knowledge bases are developed at a standard workstation which leads the developer through the language. New rules can be added in any sequence using English-like variable names and syntax.

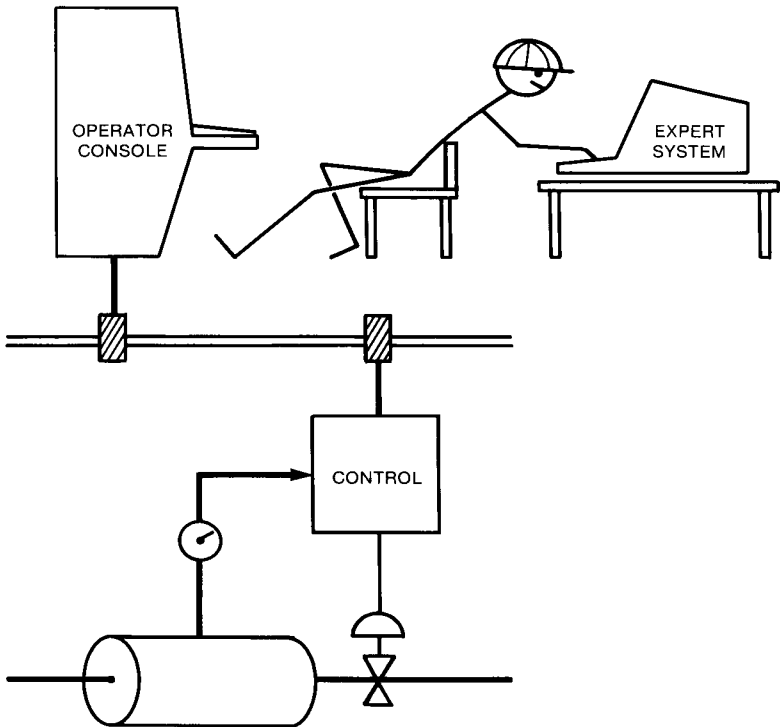


FIGURE 1a Separate Systems

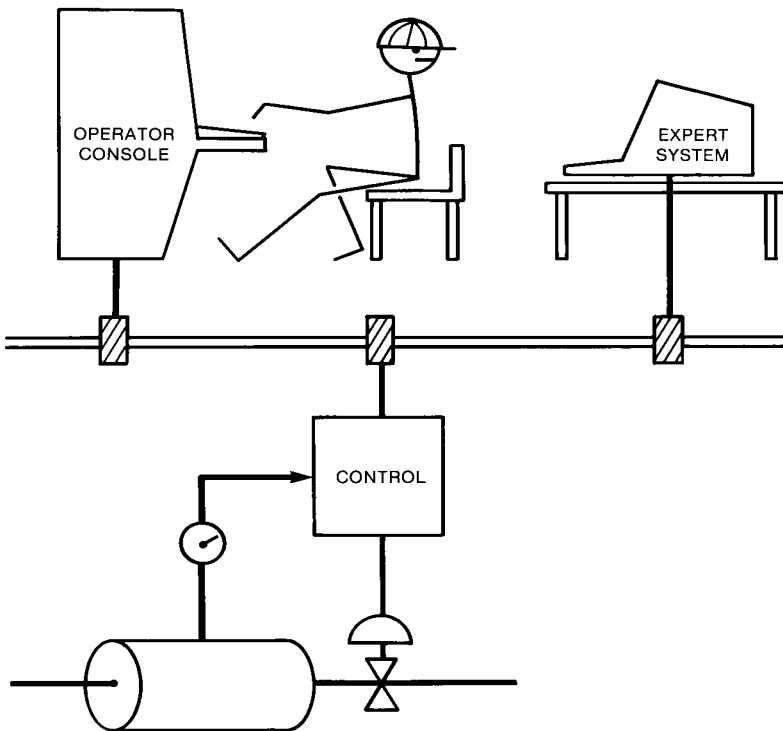


FIGURE 1b Interfaced Systems

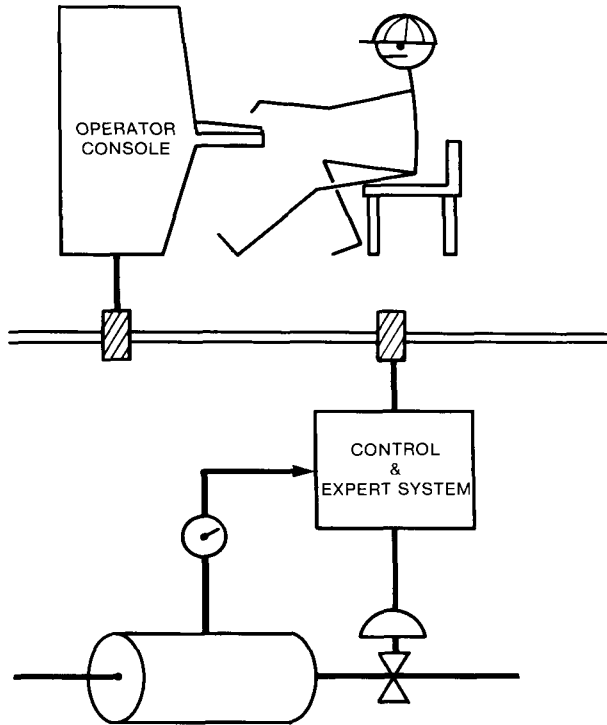


FIGURE 1c *Embed Capability*

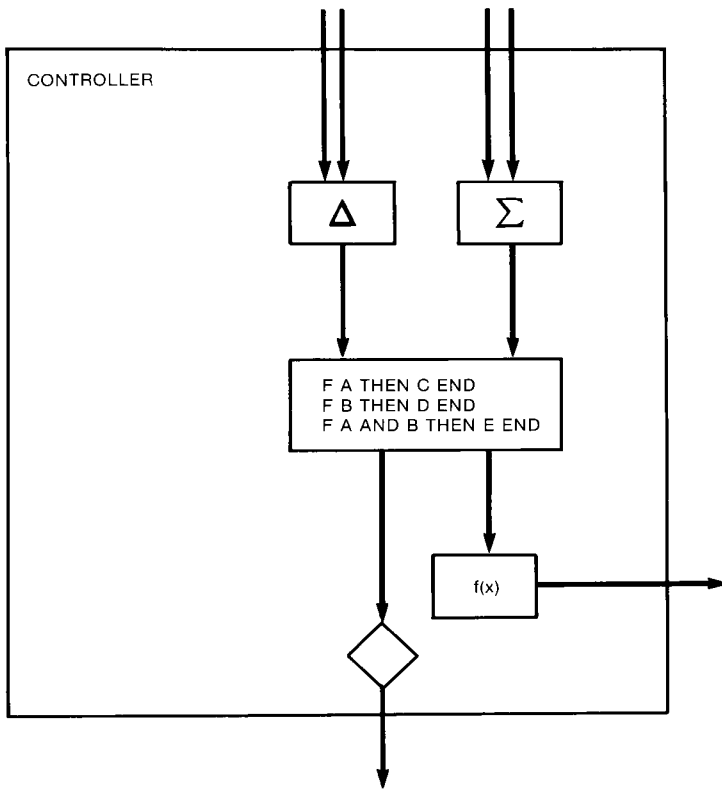


FIGURE 2 Close Up of Controller with Embedded Expert System

F CAVITATION CONDITIONS EXIST  
 AND OUTLET PRESSURE TOO LOW  
 AND RPM UNUSUALLY HIGH  
 THEN PROBABLY CAVITATING  
 AND PUMP WARNING  
 END

F PROBABLY CAVITATING OR PROBABLY STUCK OR PROBABLY LEAKING  
 THEN SET PROBLEM SITUATION  
 END

F PUMP ON AND NORMAL PRESSURE INCREASE AND NORMAL RPM  
 THEN CLEAR PROBLEM SITUATION  
 END

F FOR 15 SECONDS ((NOT RPM LOW)  
 AND OUTLET PRESSURE TOO LOW)  
 THEN PROBABLY LEAKING  
 END

F PROBABLY CAVITATING  
 THEN FOR 30 SECONDS INHIBIT PUMP ON  
 END

F JUST NOW PROBLEM SITUATION  
 THEN FOR 3 SECONDS AUDIBLE ALARM  
 END

F ACTION REQUESTED  
 THEN AFTER 60 SECONDS CHECK ACTION COMPLETED  
 END

F INCREASE FLOW  
 AND NOT FLOW BEING MANIPULATED  
 THEN FLOW SETTING (FLOW SETTING + 600) / 2  
 AND FOR 300 SECONDS FLOW BEING MANIPULATED  
 END

FIGURE 3 Logic and Timing Representation

F RPM  $\Rightarrow$  230 TO 250  
THEN RPM UNUSUALLY HIGH  
END

F PROBABLY LEAKING  
THEN PUMP PROBLEM  
AND SET PUMP ALARM  
END

F PUMP SWITCH ON  
AND RPM NEGLIGIBLE  
THEN 75% OFTEN PUMP NOT GETTING POWER  
END

F CERTAINTY PUMP FAILURE  $\Rightarrow$  30%  
THEN PUMP SUSPECT  
END

*FIGURE 4 Uncertainty Representation*



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