



## **Integrated Paper Machine Control: Past, Present, and Future**

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**INTEGRATED PAPER MACHINE CONTROL -  
PAST, PRESENT, FUTURE**

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**ABSTRACT**

The paper-making processes has undergone many changes over the years. In the past we had operators who were skilled in the 'art' and 'feel' of papermaking. Today, with sophisticated Distributed Control Systems we see a true integration of paper machine control. The traditional regulatory control, advanced control, motor start/stop, scanning sensors, drives and roll-tracking, are now integrated into a "single window" environment. Tomorrow will bring revolutionary systems such as non-scanning sensors and expert systems using the latest artificial intelligence techniques to allow the total mill to be operated in a strategic process management manner.

**INTRODUCTION**

Papermaking is no longer just an art, but a sophisticated process involving many different disciplines and control systems.

**Past** - The Paper Industry has evolved from the old M 40 roundchart recorder/controller of the 50's & 60's to the IBM 1800's, and mini-computer control systems of the 70's.

**Present** - With today's rapidly changing technology, Distributed Control systems with Multi-function controllers have the power of yesterdays main frame computers, or large panel board systems. With a single window' an operator can, with one or two keystrokes, startup and control his Paper Machine with increasing sophistication.

**Future** - Tomorrow we will see complete non-scanning sensors to measure and control high frequency disturbances. In addition, we will be able to track the total final product quality information back through the complete Pulping & Paper Making process.

**PAST**

In the first half of the 1900's Papermaking was considered an operating art. There was little instrumentation other than a few scattered indicators, gauges and recorders. Most paper machines were designed to run at speeds of less than 1000 feet per minute and trimmed less than 150 inches with manual regulations of the process and of the machine drive and components. Product testing was entirely off-line

**Early Paper Machine Gauges**

In the early 1950's some of the early gauging companies included Tracerlab, Industrial Nucleonics, Isotope Products and Curtiss Wright.

The early Basis Weight gauges were mounted on simple C Frames that often measured at a single point across the machine. To overcome the possibility of measuring at either an unrepresentative heavy or light spot across the machine, the measuring area was 14 inches in the cross-direction (CD) by two inches in the machine direction (MD). An averaging of the short term machine direction variations was achieved by using a fairly long, one to three minute response time. The gauge would respond to long term MD trends in Basis Weight but was incapable of responding to short term MD variations. In addition, due to the short C. Frame, it could not be used for cross direction profiling. [1]

Shortly after the Basis Weight gauges were introduced came the moisture gauge, both conductivity and RF types were used. The two sensors were then mounted together on a "O-Frame" to scan across the entire web. Later in the sixties came the on-line Caliper & Formation sensors. A typical Weight & Moisture direct reading system with automatic control cost between \$70-\$80K.

Often the acceptance of the gauging system by the people who were using the equipment, was predicated on the clarity and accuracy of the information presentation. Early in the on machine sensor history, direct reading scales and wide strip chart recorders were first justified to management as an operating record which could be easily interpreted by operators for control purposes and by management personnel for economic justification studies.

This conventional approach to recording the machine direction averages had the advantages of high readability, ready trend detection, and was unambiguous as a final product record. Little attention was paid to profile records from which the operator was expected to make a trend analysis and presumably take corrective action. Often the profile information was presented in such a way as to be used as a rough indication of the overall profile but of little use for fine adjustment.

The X Y recorder was an ideal solution. Basically, the X Y recorder was a modification of a standard single pen recording system but provided a means of plotting one variable as a function of another, i.e., vertical axis accepted a measured variable, and the horizontal axis represented the simultaneous position of the measuring gauge. As a historical note, the X Y recording system was originated by Noel Obenshain of Westvaco back in 1955 [2]. Typical recorder displays are shown in Figures 1 & 2.

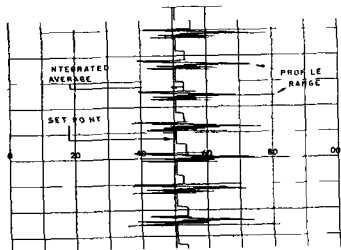


Fig. 1 Strip Chart Recorder Display

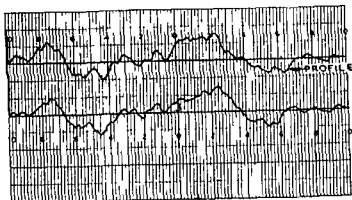
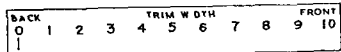


Fig 2 X Y Recorder Display

With the profile information available and with increased emphasis on the abilities to set the slice accurately, the slice lips were changed to include micrometer readouts, and motorized control was added enabling individual adjustments. This was the start of today's automatic CD Control.

In 1957 J. Franklin of Bowaters commented that before papermaking can be termed a truly automatic process, each step on the machine must be measurable and controlled, not only longitudinally, but laterally. In this field the Papermaker & Process Control Engineer meet in designing an existing future [3].

### Early Regulatory Control

In the period up to 1960 analog pneumatic control was almost exclusively used. Controls were direct connected using circular chart recorders with pressure & temperature capillaries. Then there was a major conversion to transmitting systems. With pneumatic transmitters, measurements were converted to pneumatic signals of a fixed range which were transmitted to a receiver located in a control center. Controllers in the control center then computed (pneumatically) the appropriate control actions which were again transmitted back to the field located regulating devices such as valves, drives and others. With transmission based systems, there was a considerable reduction of installed control system costs.

Paper Machines were being instrumented using groups of instrument control centers rather than scattered instrumentation. Operating instrument control centers were beginning to be designed for Stock Blending, Paper Machine Wet End, Press Section, and Dryer Sections. Many control centers had attractive color graphic layouts of their control process [4].

### Early Computer Control

There were two types of early computer control systems. First, the large main frame (IBM 1800) types used to automate or control the complete Papermaking process. Second, we had the small mini computer (32K), Packaged Control System supplied by the various gauging companies.

With both of these types of computer control systems came the first use of CRT displays and typewriter printers. Operator interfaces became much more extensive with modern keyboards, video displays and customized printed reports. These systems represented a combination of supervisory & direct digital control. Many control loops had analog backup controllers function as digital-to-analog converters in the computer mode and could be switched either automatically or manually.

As experience with these systems grew, operator acceptance increased. It was found that when a computer was added to the system the increase in uniformity was usually not spectacular. The reason for this is that the two main points with a computer were its speed of operation and its memory. With a Dry End beta gauge controlling the stock valve, the computers speed and memory were of little value. However, if the computer was used with flow and consistency data gathered at the headbox, the computer had the ability to predict what the basis weight would be at the reel. In this feed forward type of control the computer excelled and substantial improvements in short term control uniformity could be achieved.

As process control computers became more popular in the mid 1970's, there was a technological shift away from the pneumatic control panels and we found the all electronic system. Computers and application packages were becoming available at lower initial cost. We also found that the new solid state electronic transmitters offered better accuracy, repeatability and dependability while reducing maintenance. Microprocessor based systems are now available which encompass all elements of control including those previously handled by separate programmable logic controllers and analog system in a single product line.

The results and acceptance of these early Paper Machine Computer Control systems have been well documented. In most cases these systems, some installed two decades ago, are just now being replaced with the next generation of control; the microprocessor based Distributed Control System.

#### PRESENT

##### Distributed Control Systems

With today's microprocessor technology the role of the Distributed Control System has expanded from one of replacing analog instrumentation to

having the potential in both size and function to be the backbone of the Millwide Control System. We have seen Distributed Control Systems fully distributing the measurement and control functions that previously were accomplished in larger single computer systems.

A modern Distributed Control System (DCS) must have the architecture to properly partition the control function narrow enough so that a single point of failure does not require a total system shutdown. It must offer technological transparency to allow today's systems to be compatible with tomorrow's technology. The vendor must strive to keep his product contemporary to sustain new business, but must also continue to provide parts and service for the installed life of the products.

Today's systems require an open system architecture where communications are possible both horizontally and vertically at all levels.

Module to Module

Module to Foreign Device

Process Unit to Process Unit

System to System

System to Computer

Recently multifunction controllers (MFC's) have been introduced with more power and flexibility than ever before. 32 bit microprocessor, full redundancy multi-tasking, over 280K bytes of memory.

One of the most difficult historical problems, both for control vendors and users, has been control system obsolescence. Both vendors and users are driven by the apparently diametrically opposed needs to have the benefits of the latest technology while avoiding the cost and production interruptions associated with periodic total replacement of instrumentation systems. [8]

Several of today's systems have the ability to provide direct access to configuration data through the use of a Personal Computer or Engineering Work Station.

Configuration is referred to in today's DCS as the "programming" of the control logic. This is primarily done in SAMA language function codes. (See Figures 3 & 4). This allows the Control Engineer the ability to see the process through a glass box rather than the

"black box of software extensive system of yesterday. The Engineering Work Station (EWS) provides configuration, tuning and documentation support to the Engineering & Maintenance personnel. Configurations may be generated off line without affecting control or interfering with the process operators. The new or revised configurations can be stored on diskettes and/or directly downloaded to the DCS. Using the Computer Assisted Drawing (CAD) software, configuration loop/logic drawings are generated concurrently with the configuration design, providing a powerful and accurate documentation standard [6]

**Systems Integration**

An objective of today's DCS is to provide one integrated system capable of handling all process control functions (formerly handled by several systems (PLC's, controllers, computers, etc.). A modern system must be capable of easily and cost effectively integrating the following control functions

- Basic Regulatory Loops
- Motor Start/Stop Controls
- Interlocking & Sequential Functions
- Advanced/Multi Variable Control Strategies
- Complex Mathematical Process Models for Optimization

It has been the writers experience that PLC's are used with interfaces to the DCS only where they presently exist before modernization, where there are separate instrument/electrical maintenance jurisdictions, or when there is a very high concentrated number of digital I/O. In normal Paper Machine modernizations, motor start/stop functions are totally integrated into the DCS. When using either DCS's or PLC's, scan time should be kept in mind especially where quick control speed is critical

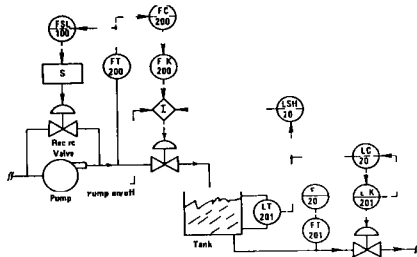


Figure 3: Level Control P&ID

Interfacing DCS's to other foreign devices, i.e., Gauging Systems, Drive Systems, Roll Finishing Systems, etc., is usually accomplished by using an RS 232C serial interface. These interfaces are usually fairly straightforward using standard protocol. In some cases the user friendliness of two devices becomes political at which time the end user needs to clarify which vendor is responsible for what. See Figure 5

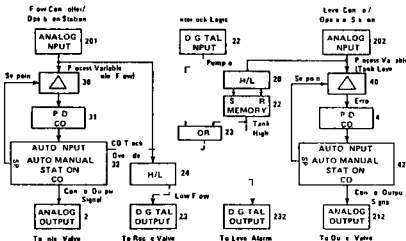


Fig 4 Level Control SAMA (Function Code) Logic

	C N DA P O SE F M U ER	D O CATED UPRRT COMPUTER	D S O RUTED CONTROL SYS IN	PPROGRAMMABLE LOG C CONTROLLER
PLS	■	■	■	■
DATA H G WAY COMPUTER NETWORKS	■	■	■	■
OPERATOR CONSOLE	■	■	■	■
ADVANCED CONTROL	■	■	■	■
REGULATORY CONTROL	■	■	■	■
P SECTE/ABC CONTROL	■	■	■	■
SENSOR/ANALYZER INTERFACE	■	■	■	■
ANALOG /O	■	■	■	■
D SCRTE /O	■	■	■	■

Fig 5 Millwilde Control System Selection Guide



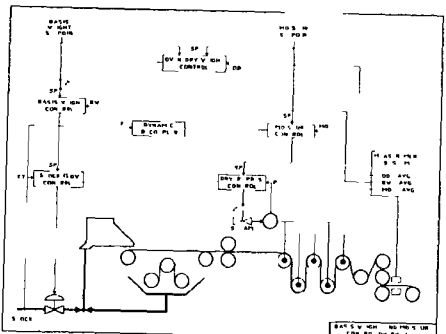


Fig 9 Basis Weight & Moisture  
COORDINATED GRADE CHANGE TABLE F20A

DESCR PTION	WIRE	NO	OF	STKS	ED	1	STRESS	GRADE CHANGE					
1) REFORM	8	PLATO	15	78	50	839	3	1	33	1	42	STRESS	NO
2) INK SPEC ENERGY	87	CRMC	24	6	24	-	3	32	3	1	42	STRESS	NO
3) INK FLAM	82	CRMC	79	792	696	39	206	43	8	1	42	STRESS	NO
4) WIRE SPEED	84	PLATO	6	25	424	845	26	624	64	1	42	STRESS	NO
5) WIRE PROFILE NO	86	CRMC	6	80	35	8	20	45	1	42	STRESS	NO	
6) VERTICAL SLICE	88	CRMC	6	82	8	36	-	-	-	-	-	-	-
7) HORIZONTAL SLICE	87	CRMC	8	82	2	2	3	37	1	42	STRESS	NO	
8) JET Y WIRE PIV G	88	PLATO	6	80	35	8	20	45	1	42	STRESS	NO	
9) HEADON FLOW	83	PLATO	6	80	35	8	20	45	1	42	STRESS	NO	
10) REELING 8TH PRESS	8	PLATO	6	80	35	8	20	45	1	42	STRESS	NO	
11) 8A 5 DRIVER PRESSURE	1	PLATO	6	80	35	8	20	45	1	42	STRESS	NO	
12) 8A 5 DRIVER 8 FF PRES	2	CRMC	6	79	7	86	5	76	42	5	42	STRESS	NO
13) 8T SECT ON PRESSURE	3	CRMC	4	2	4	7	8	43	7	8	42	STRESS	NO
14) 8T SECT ON 8FF PRES	4	CRMC	6	80	7	80	44	7	80	7	42	STRESS	NO
15) 8T2 SECT ON PRESSURE	5	CRMC	43	64	6	6	45	87	6	42	STRESS	NO	
16) 8T2 SECT ON 8FF PRES	6	CRMC	2	2	4	3	4	45	3	4	42	STRESS	NO
17) 8T2 8FF DRIVER PRESS	7	AUTO	6	80	35	8	20	45	1	42	STRESS	NO	
18) 8T2 8FF DRIVER 8FF PRES	8	AUTO	6	80	35	8	20	45	1	42	STRESS	NO	
19) 8T2 PRESS NO STURE	9	AUTO	6	80	35	8	20	45	1	42	STRESS	NO	
20) 8T2 PRESS 8FF PRES	10	AUTO	6	80	35	8	20	45	1	42	STRESS	NO	
21) 8T2 PRESS WEIGHT	11	AUTO	6	80	35	8	20	45	1	42	STRESS	NO	
22) 8T2 PRESS NO STURE	12	AUTO	6	80	35	8	20	45	1	42	STRESS	NO	
23) 8T2 PRESS 8FF PRES	13	AUTO	6	80	35	8	20	45	1	42	STRESS	NO	
24) 8T2 PRESS WEIGHT	14	AUTO	6	80	35	8	20	45	1	42	STRESS	NO	
25) 8T2 PRESS NO STURE	15	AUTO	6	80	35	8	20	45	1	42	STRESS	NO	
26) 8T2 PRESS 8FF PRES	16	AUTO	6	80	35	8	20	45	1	42	STRESS	NO	
27) 8T2 PRESS WEIGHT	17	AUTO	6	80	35	8	20	45	1	42	STRESS	NO	
28) 8T2 PRESS NO STURE	18	AUTO	6	80	35	8	20	45	1	42	STRESS	NO	
29) 8T2 PRESS 8FF PRES	19	AUTO	6	80	35	8	20	45	1	42	STRESS	NO	
30) 8T2 PRESS WEIGHT	20	AUTO	6	80	35	8	20	45	1	42	STRESS	NO	
31) 8T2 PRESS NO STURE	21	AUTO	6	80	35	8	20	45	1	42	STRESS	NO	
32) 8T2 PRESS 8FF PRES	22	AUTO	6	80	35	8	20	45	1	42	STRESS	NO	
33) 8T2 PRESS WEIGHT	23	AUTO	6	80	35	8	20	45	1	42	STRESS	NO	
34) 8T2 PRESS NO STURE	24	AUTO	6	80	35	8	20	45	1	42	STRESS	NO	
35) 8T2 PRESS 8FF PRES	25	AUTO	6	80	35	8	20	45	1	42	STRESS	NO	
36) 8T2 PRESS WEIGHT	26	AUTO	6	80	35	8	20	45	1	42	STRESS	NO	
37) 8T2 PRESS NO STURE	27	AUTO	6	80	35	8	20	45	1	42	STRESS	NO	
38) 8T2 PRESS 8FF PRES	28	AUTO	6	80	35	8	20	45	1	42	STRESS	NO	
39) 8T2 PRESS WEIGHT	29	AUTO	6	80	35	8	20	45	1	42	STRESS	NO	
40) 8T2 PRESS NO STURE	30	AUTO	6	80	35	8	20	45	1	42	STRESS	NO	
41) 8T2 PRESS 8FF PRES	31	AUTO	6	80	35	8	20	45	1	42	STRESS	NO	
42) 8T2 PRESS WEIGHT	32	AUTO	6	80	35	8	20	45	1	42	STRESS	NO	
43) 8T2 PRESS NO STURE	33	AUTO	6	80	35	8	20	45	1	42	STRESS	NO	
44) 8T2 PRESS 8FF PRES	34	AUTO	6	80	35	8	20	45	1	42	STRESS	NO	
45) 8T2 PRESS WEIGHT	35	AUTO	6	80	35	8	20	45	1	42	STRESS	NO	
46) 8T2 PRESS NO STURE	36	AUTO	6	80	35	8	20	45	1	42	STRESS	NO	
47) 8T2 PRESS 8FF PRES	37	AUTO	6	80	35	8	20	45	1	42	STRESS	NO	
48) 8T2 PRESS WEIGHT	38	AUTO	6	80	35	8	20	45	1	42	STRESS	NO	
49) 8T2 PRESS NO STURE	39	AUTO	6	80	35	8	20	45	1	42	STRESS	NO	
50) 8T2 PRESS 8FF PRES	40	AUTO	6	80	35	8	20	45	1	42	STRESS	NO	
51) 8T2 PRESS WEIGHT	41	AUTO	6	80	35	8	20	45	1	42	STRESS	NO	
52) 8T2 PRESS NO STURE	42	AUTO	6	80	35	8	20	45	1	42	STRESS	NO	
53) 8T2 PRESS 8FF PRES	43	AUTO	6	80	35	8	20	45	1	42	STRESS	NO	
54) 8T2 PRESS WEIGHT	44	AUTO	6	80	35	8	20	45	1	42	STRESS	NO	
55) 8T2 PRESS NO STURE	45	AUTO	6	80	35	8	20	45	1	42	STRESS	NO	
56) 8T2 PRESS 8FF PRES	46	AUTO	6	80	35	8	20	45	1	42	STRESS	NO	
57) 8T2 PRESS WEIGHT	47	AUTO	6	80	35	8	20	45	1	42	STRESS	NO	
58) 8T2 PRESS NO STURE	48	AUTO	6	80	35	8	20	45	1	42	STRESS	NO	
59) 8T2 PRESS 8FF PRES	49	AUTO	6	80	35	8	20	45	1	42	STRESS	NO	
60) 8T2 PRESS WEIGHT	50	AUTO	6	80	35	8	20	45	1	42	STRESS	NO	
61) 8T2 PRESS NO STURE	51	AUTO	6	80	35	8	20	45	1	42	STRESS	NO	
62) 8T2 PRESS 8FF PRES	52	AUTO	6	80	35	8	20	45	1	42	STRESS	NO	
63) 8T2 PRESS WEIGHT	53	AUTO	6	80	35	8	20	45	1	42	STRESS	NO	
64) 8T2 PRESS NO STURE	54	AUTO	6	80	35	8	20	45	1	42	STRESS	NO	
65) 8T2 PRESS 8FF PRES	55	AUTO	6	80	35	8	20	45	1	42	STRESS	NO	
66) 8T2 PRESS WEIGHT	56	AUTO	6	80	35	8	20	45	1	42	STRESS	NO	
67) 8T2 PRESS NO STURE	57	AUTO	6	80	35	8	20	45	1	42	STRESS	NO	
68) 8T2 PRESS 8FF PRES	58	AUTO	6	80	35	8	20	45	1	42	STRESS	NO	
69) 8T2 PRESS WEIGHT	59	AUTO	6	80	35	8	20	45	1	42	STRESS	NO	
70) 8T2 PRESS NO STURE	60	AUTO	6	80	35	8	20	45	1	42	STRESS	NO	
71) 8T2 PRESS 8FF PRES	61	AUTO	6	80	35	8	20	45	1	42	STRESS	NO	
72) 8T2 PRESS WEIGHT	62	AUTO	6	80	35	8	20	45	1	42	STRESS	NO	
73) 8T2 PRESS NO STURE	63	AUTO	6	80	35	8	20	45	1	42	STRESS	NO	
74) 8T2 PRESS 8FF PRES	64	AUTO	6	80	35	8	20	45	1	42	STRESS	NO	
75) 8T2 PRESS WEIGHT	65	AUTO	6	80	35	8	20	45	1	42	STRESS	NO	
76) 8T2 PRESS NO STURE	66	AUTO	6	80	35	8	20	45	1	42	STRESS	NO	
77) 8T2 PRESS 8FF PRES	67	AUTO	6	80	35	8	20	45	1	42	STRESS	NO	
78) 8T2 PRESS WEIGHT	68	AUTO	6	80	35	8	20	45	1	42	STRESS	NO	
79) 8T2 PRESS NO STURE	69	AUTO	6	80	35	8	20	45	1	42	STRESS	NO	
80) 8T2 PRESS 8FF PRES	70	AUTO	6	80	35	8	20	45	1	42	STRESS	NO	
81) 8T2 PRESS WEIGHT	71	AUTO	6	80	35	8	20	45	1	42	STRESS	NO	
82) 8T2 PRESS NO STURE	72	AUTO	6	80	35	8	20	45	1	42	STRESS	NO	

Fig 10 Coordinated Grade Change Table Graphic

Operator Interfaces

Today's operator consoles with high resolution CRT touch screen displays are a far cry from yesterday's strip chart, nixie tube readings. Modern systems offer tag or point capabilities of over 20,000. They have the ability to provide sophisticated trending and logging features which allow the operator to retrieve operating data from several months past. Displays are easily designed and configured with free format display hierarchy. All displays have the capability of being customized by the operator. With graphic capabilities of several thousand pages the DCS can truly be a window into the process.

Alarm Management

With the ability of today's systems to control the complete process from one console containing many thousand control points, the issue of process alarms needs to be addressed. How many times have operator consoles been observed with flashing unacknowledged alarms? Systems now have multi level alarm management capabilities and event alarm suppression. Why, when during a sheet break, have numerous slow and rate alarms going off when this is a completely normal condition when that event (sheet break) occurs? Why not have these certain new alarm limits set when certain events occur? Most systems have dedicated panels or graphic pages devoted just for alarm annunciation. This allows the operator with minimal key strokes to identify the alarm and take corrective action. A challenge exists to both the systems designers and mill operations to engineer alarm management into the system correctly so we can eliminate the necessity of operators monitoring (or ignoring) meaningless alarms.

Statistical Process Control (SPC)

In the last several years the application of statistical process control (SPC) has become a prime issue in this industry. Increased resource costs and global competition have rostered the spread of the computerized Statistical Quality Control (SQC) techniques and Statistical Process Control (SPC) procedures from discrete manufacturing operations to continuous processing operations. Advances in technology have allowed these statistical operations to be performed or accomplished on line in the DCS [7].

FUTURE

As Chris Ljakos wrote, "Someone once said, if he knew he had been living in an era, he would have paid more attention to what was going on around him at the time." [8] The next era is here so we must pay attention. We have heard and seen the start of millwide systems. These systems will continue to evolve and allow optimization of all individual mill process units and the coordination of each area to one total mill operating plan. In doing so, mill management will have real, on line control of production, rates, material, inventories and schedules.

Areas that will have a major impact on the next era are

- Non scanning Paper Machine Sensors
- Process Optimization
- Expert Systems
- Strategic Process Management

#### Non Scanning Paper Machine Sensor

As this paper reflects, paper machine gauging systems have been with us for over a quarter of a century. Even though there have been six generations of sensor development, the technique of scanning the sheet has changed very little. We are beginning to see various non scanning individual sensors. When development of the full complement of the basic measurements is accomplished, (weight, moisture, caliper) then high frequency, minute measurements can provide a new dimension in paper machine control.

#### Process Optimization

Process optimization is one of the main goals of a millwide system. It can be utilized to minimize mill operating costs by actively supervising the various production departments within the mill, including the paper machine. The major economic benefits are in the area of increased production and reduced operating cost.

By maximizing production, a grade target structure can be entered into the system and it will determine optimal inventory targets and coordinate production rates for all operating departments. This results in reducing operational disturbances, improving optimal production planning, quality control, energy production coordination and energy management.

#### Expert Systems

The uses of Expert Systems and Artificial Intelligence is increasing at a high rate. Expert Systems are rapidly moving out of the off line environment and into on line process control applications, usually integrated with today a distributed control system.

The field of Expert Systems can be defined as the branch of Artificial Intelligence that attempts to model and retrieve human knowledge about objective concepts, facts and their relationships.

An example of an Expert System for the paper machine area is to optimize the furnish blend and operating parameters for the development of new paper grades by efficiently reviewing and selecting bits of previous production strategy which lend themselves to meeting customer specifications.

The era of large stand alone computers running Expert Systems is over. Expert Systems will be embedded in process control systems in multiple distributed modules. These distributed Expert Systems will be available and cost effective for a large number of applications at a minimum cost to the user [10].

#### Strategic Process Management

With our today's increased global competition in our industry, the need to focus on improving profitability and quality will require us to look at a higher level of control. Strategic Process Management. This represents the top of the control hierarchy and may be the objective of mill management. With the utilization of the full power of modern distributed control systems this is capable of achievement.

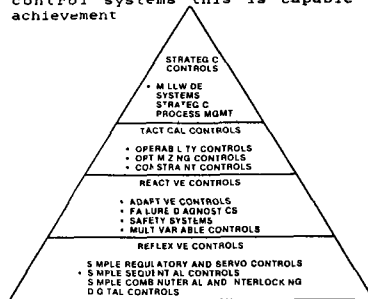


Figure 11 The Control Hierarchy

The key objective to a plant wide strategic process management system should be to automate process operations as much as practical, and present information critical for control cost analysis of current and future operations. Further it should also provide a communication system for implementing operational plans

It is evident that significant cost savings can be achieved through coordination of the complex production, quality, energy and maintenance functions of an integrated mill. This forms the essence of Strategic Process Management. The synergistic benefit of properly integrated and coordinated controls yields a whole (total mill wide control), which is greater than some of its component parts (unit optimizations). [11]

#### CONCLUSION

Paper Machine Control has changed considerably over the last three decades. We have seen it change from total manual control to a cumbersome main frame computer control to today's user friendly system using the latest microprocessor technology. Tomorrow we will see total plant wide optimization, and we will continue to evolve through the many changes and operations characteristic of a natural progression

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